

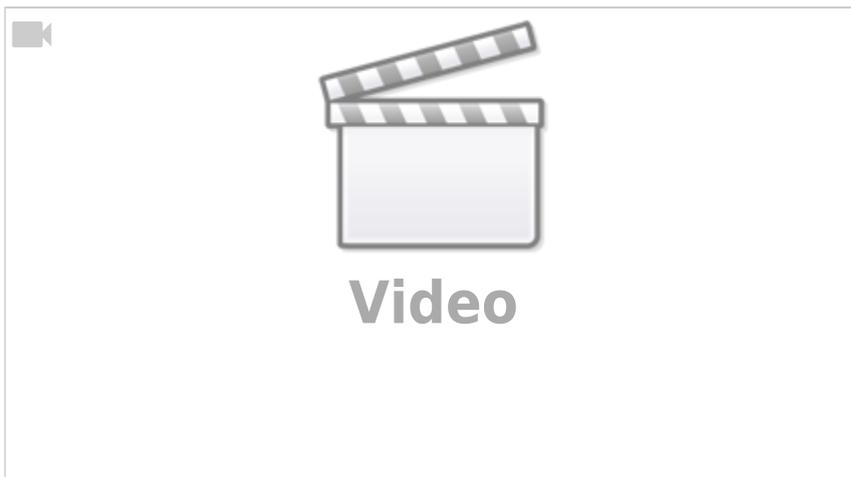


飛行模擬器



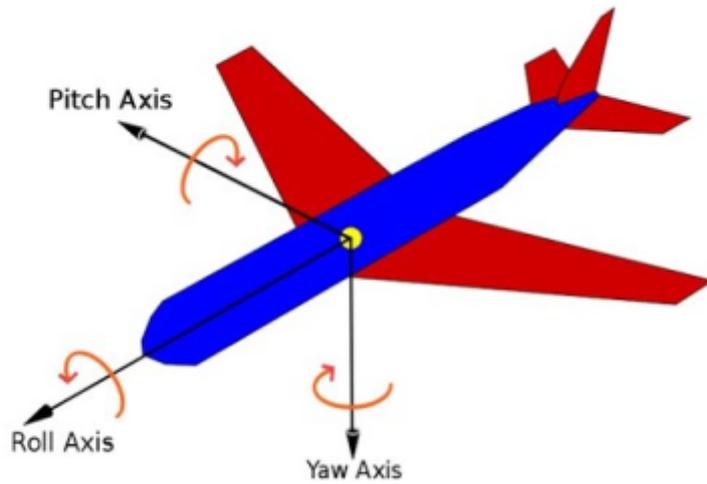
組裝圖

示範影片



飛行姿態

PITCH ROLL YAW



參考程式

A screenshot of a MicroPython code editor. The code consists of three blocks: 1. A 'When started' block (當啟動時) with a servo motor control block. 2. A 'Repeat indefinitely' block (重複無限次) containing a servo motor control block. 3. A 'Pause' block (暫停) set to 100 milliseconds. The servo motor control block is configured with: Pin: P0, Range: 90, and Sensor: roll (rotation sensor value in degrees).

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